

Product data sheet

Specifications



servo motor BMH, Lexium 32,
3.4Nm, 8000rpm, untapped shaft,
with brake, IP54, 16 multiturn
encoder, 3 phases

BMH0703P07F2A

Main

Device Short Name	BMH
Product Or Component Type	Servo motor
Maximum Mechanical Speed	8000 rpm
Continuous Stall Torque	30.09 lbf.in (3.4 N.m) LXM32.D18N4 6 A, 400 V, three phase 30.09 lbf.in (3.4 N.m) LXM32.D18N4 6 A, 480 V, three phase
Peak Stall Torque	90.28 lbf.in (10.2 N.m) LXM32.D18N4 6 A, 400 V, three phase 90.28 lbf.in (10.2 N.m) LXM32.D18N4 6 A, 480 V, three phase
Nominal Output Power	1300 W LXM32.D18N4 6 A, 400 V, three phase 1300 W LXM32.D18N4 6 A, 480 V, three phase
Nominal Torque	21.24 lbf.in (2.4 N.m) LXM32.D18N4 6 A, 400 V, three phase 21.24 lbf.in (2.4 N.m) LXM32.D18N4 6 A, 480 V, three phase
Nominal Speed	5000 rpm LXM32.D18N4 6 A, 400 V, three phase 5000 rpm LXM32.D18N4 6 A, 480 V, three phase
Product Compatibility	LXM32.D18N4 400...480 V three phase
Shaft End	Smooth shaft
Ip Degree Of Protection	IP54 standard
Speed Feedback Resolution	32768 points/turn x 4096 turns
Holding Brake	With
Mounting Support	International standard flange
Electrical Connection	Rotatable right-angled connectors

Complementary

Range Compatibility	Lexium 32
[Us] Rated Supply Voltage	480 V
Phase	Three phase
Continuous Stall Current	3.91 A
Continuous Power	1.68 W
Maximum Current Irms	12.6 A LXM32.D18N4
Maximum Permanent Current	12.57 A
Second Shaft	Without second shaft end
Shaft Diameter	0.55 in (14 mm)

Disclaimer: This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications



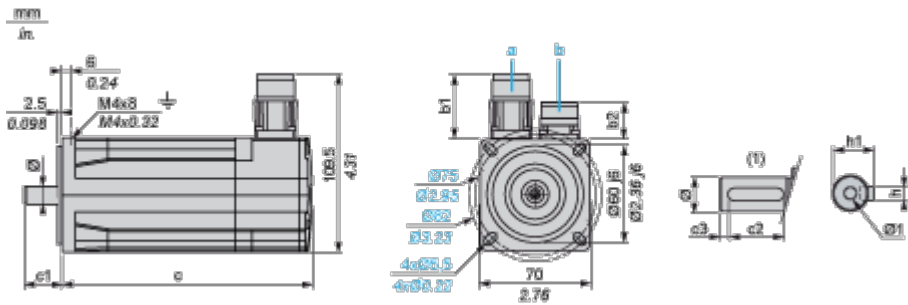
Shaft Length	1.18 in (30 mm)
Feedback Type	Multiturn SinCos Hiperface
Holding Torque	26.55 lbf.in (3 N.m) holding brake
Motor Flange Size	2.76 in (70 mm)
Number Of Motor Stacks	3
Torque Constant	0.87 N.m/A 248 °F (120 °C)
Back Emf Constant	55.8 V/krpm 248 °F (120 °C)
Number Of Motor Poles	10
Rotor Inertia	1.78 kg.cm²
Stator Resistance	2.65 Ohm 68 °F (20 °C)
Stator Inductance	8.6 mH 68 °F (20 °C)
Stator Electrical Time Constant	3.2 ms 68 °F (20 °C)
Maximum Radial Force Fr	730 N 1000 rpm 580 N 2000 rpm 510 N 3000 rpm 460 N 4000 rpm 430 N 5000 rpm 400 N 6000 rpm
Maximum Axial Force Fa	0.2 x Fr
Brake Pull-In Power	7 W
Type Of Cooling	Natural convection
Length	8.86 in (225 mm)
Centring Collar Diameter	2.36 in (60 mm)
Centring Collar Depth	0.10 in (2.5 mm)
Number Of Mounting Holes	4
Mounting Holes Diameter	0.22 in (5.5 mm)
Circle Diameter Of The Mounting Holes	3.23 in (82 mm)
Net Weight	8.82 lb(US) (4 kg)



Dimensions Drawings

Servo Motors Dimensions

Example with Straight Connectors



- a: Power supply for servo motor brake
- b: Power supply for servo motor encoder
- (1) Shaft end, keyed slot (optional)

Dimensions in mm

Straight connectors		Rotatable angled connectors		c (without brake)	c (with brake)	c1	c2	c3	h	h1	Ø	Ø1 for screws
b1	b2	b1	b2									
39.5	25.5	39.5	39.5	186	225	30	20	5	5 h9	16 ⁺⁰ _{-0.13}	14 k6	M5 x 17

Dimensions in in.

Straight connectors		Rotatable angled connectors		c (without brake)	c (with brake)	c1	c2	c3	h	h1	Ø	Ø1 for screws
b1	b2	b1	b2									
1.55	1	1.55	1.55	7.32	8.85	1.18	0.78	0.19	0.20 h9	0.63 ⁺⁰ _{-0.0051}	0.55 k6	M5 x 0.67

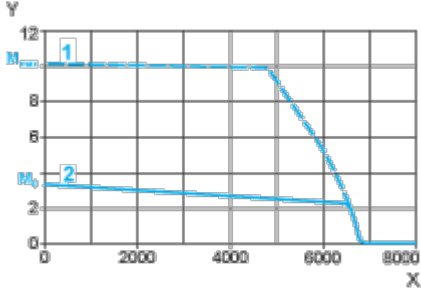


Performance Curves

400 V 3-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32-D18N4 servo drive



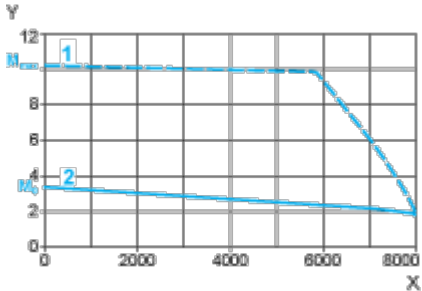
- X Speed in rpm
- Y Torque in Nm
- 1 Peak torque
- 2 Continuous torque



480 V 3-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32•D18N4 servo drive



- X Speed in rpm
- Y Torque in Nm
- 1 Peak torque
- 2 Continuous torque